



A remark on the Laplacian flow and the modified Laplacian co-flow in G_2 -geometry

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Abstract

We give a shorter proof of the well-posedness of the Laplacian flow in G_2 -geometry. This is based on the observation that the DeTurck–Laplacian flow of G_2 -structures introduced by Bryant and Xu as a gauge fixing of the Laplacian flow can be regarded as a flow of (not necessarily closed) G_2 -structures, which fits in the general framework introduced by Hamilton in *J Differ Geom* 17(2):255–306, 1982. A similar application is given for the modified Laplacian co-flow.

Keywords Laplacian flow · G_2 -geometry · Short-time existence

1 Introduction

In [1] Bryant introduced a geometric flow in G_2 -geometry which evolves an initial closed G_2 -structure φ_0 in the direction of its Laplacian.

Given a compact seven-dimensional manifold with a closed G_2 -structure (M, φ_0) , a *Laplacian flow* is a solution to the evolution equation

$$\frac{\partial}{\partial t} \varphi_t = \Delta_{\varphi_t} \varphi_t, \quad d\varphi_t = 0, \quad \varphi_{|t=0} = \varphi_0. \quad (1)$$

The well-posedness of Eq. (1) is proved in [2] by applying the Nash–Moser theorem to the gauge fixing

$$\frac{\partial}{\partial t} \varphi_t = \Delta_{\varphi_t} \varphi_t + \mathcal{L}_{V(\varphi_t)} \varphi_t, \quad d\varphi_t = 0, \quad \varphi_{|t=0} = \varphi_0, \quad (2)$$

where \mathcal{L} is the Lie derivative and $V : C^\infty(M, \Lambda_+^3) \rightarrow C^\infty(M, TM)$ is a first-order differential operator which depends on the choice of a connection on M . Here, Λ_+^3 denotes the open

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subbundle of Λ^3 of G_2 -structures on M . A solution to (2) is usually called a *DeTurck–Laplacian flow*.

A DeTurck–Laplacian flow φ_t is also a solution to

$$\frac{\partial}{\partial t} \varphi_t = dd^*_{\varphi_t} \varphi_t + d_{V(\varphi_t)} \varphi_t, \quad \varphi_{|t=0} = \varphi_0. \tag{3}$$

In the present note, we observe that Eq. (3) fits in the general framework introduced by Hamilton in [4]. As a direct consequence, we have the following theorem which in particular implies the well-posedness of (2)

Theorem 1.1 *Let (M, φ_0) be a compact seven-dimensional manifold with a G_2 -structure. Then, Eq. (3) has a unique short-time solution.*

In [5] Kariyannis, McKay and Tsui introduced the *Laplacian co-flow* as the solution to the evolution equation

$$\frac{\partial}{\partial t} (*_{\varphi_t} \varphi_t) = -\Delta_{\varphi_t} *_{\varphi_t} \varphi_t, \quad d *_{\varphi_t} \varphi_t = 0, \quad \varphi_{|t=0} = \varphi_0, \tag{4}$$

where in this case φ_0 is supposed to be co-closed with respect to the metric induced by itself. The well-posedness of this last equation is still an open problem and Grigorian introduced in [3] the following modification

$$\frac{\partial}{\partial t} (*_{\varphi_t} \varphi_t) = \Delta_{\varphi_t} *_{\varphi_t} \varphi_t + 2d((A - \text{Tr}(T(\varphi_t)))\varphi_t), \quad d *_{\varphi_t} \varphi_t = 0, \quad \varphi_{|t=0} = \varphi_0, \tag{5}$$

where A is a constant and $T(\varphi_t)$ is the torsion of φ_t . In [3], the well-posedness of (5) is proved following the same approach of Bryant in [1] by applying the Nash–Moser theorem to the gauge fixing

$$\frac{\partial}{\partial t} (*_{\varphi_t} \varphi_t) = \Delta_{\varphi_t} *_{\varphi_t} \varphi_t + 2d((A - \text{Tr}(T(\varphi_t)))\varphi_t) + \mathcal{L}_{V(\varphi_t)} \varphi_t, \quad d *_{\varphi_t} \varphi_t = 0, \quad \varphi_{|t=0} = \varphi_0, \tag{6}$$

Any solution to Eq. (6) satisfies

$$\frac{\partial}{\partial t} (*_{\varphi_t} \varphi_t) = dd^*_{\varphi_t} *_{\varphi_t} \varphi_t + 2d((A - \text{Tr}(T(\varphi_t)))\varphi_t) + d_{V(\varphi_t)} \varphi_t, \quad \varphi_{|t=0} = \varphi_0, \tag{7}$$

Analogously to Theorem 1.1, we have

Theorem 1.2 *Let (M, φ_0) be a compact seven-dimensional manifold with a G_2 -structure. Then, Eq. (6) has a unique short-time solution.*

2 Proof of the results

Both Theorems 1.1 and 1.2 can be proved by using the following setup introduced by Hamilton in [4].

Let M be an oriented compact manifold, F a vector bundle over M , U an open subbundle of F and

$$E : C^\infty(M, U) \rightarrow C^\infty(M, F)$$

a second-order differential operator. For $f \in C^\infty(M, U)$, we denote by $DE(f) : C^\infty(M, F) \rightarrow C^\infty(M, F)$ the linearization of E at f and by $\sigma DE(f)$ the principal symbol of $DE(f)$.

Definition 2.1 *An integrability condition for E is a first-order linear differential operator*

$$L : C^\infty(M, F) \rightarrow C^\infty(M, G),$$

where G is another vector bundle over M , such that $L(E(f)) = 0$ for all $f \in C^\infty(M, U)$, and for every (x, ξ) in T^*M all the eigenvalues of $\sigma DE(f)(x, \xi)$ restricted to $\ker \sigma L(x, \xi)$ have strictly positive real part.

Theorem 2.1 (Hamilton [4, Theorem 5.1]) *Assume that E admits an integrability condition. Then, for every $f_0 \in C^\infty(M, U)$ the geometric flow*

$$\frac{\partial f}{\partial t} = E(f), \quad f(0) = f_0, \quad (8)$$

has a unique short-time solution.

Now we can focus on the setup of Theorem 1.1. Here, we consider

$$F = \Lambda^3, \quad U = \Lambda_+^3, \quad G = \Lambda^4, \quad E(\varphi) = dd_\varphi^* \varphi + d_{1_{V(\varphi)}} \varphi, \quad L = d : C^\infty(M, \Lambda^3) \rightarrow C^\infty(M, \Lambda^4).$$

From [2], it follows that for every $\varphi \in C^\infty(M, U)$ and every closed $\psi \in C^\infty(M, \Lambda^3)$, we have

$$DE(\varphi)(\psi) = -\Delta_\varphi \psi + \text{l.o.t.}$$

Hence, all the assumptions of Hamilton's Theorem 2.1 are satisfied and Theorem 1.1 follows.

Notice that if the starting form φ_0 is closed, then the solution to (3) is closed for every t since

$$d \frac{\partial}{\partial t} \varphi = 0.$$

Therefore, if φ_0 is closed, the unique solution φ_t to (3) solves also the DeTurck–Laplacian flow (2) and the short-time existence of the DeTurck–Laplacian flow (2) can be deduced from Theorem 1.1.

About the proof of Theorem 1.2, we set

$$F = \Lambda^4, \quad U = \Lambda_+^4, \quad G = \Lambda^5, \quad E(*_\varphi \varphi) = dd_\varphi^* \varphi + d_{1_{V(\varphi)}} \varphi + 2d((A - \text{Tr}(T(\varphi)))\varphi), \\ L = d : C^\infty(M, \Lambda^4) \rightarrow C^\infty(M, \Lambda^5).$$

From [3], it follows

$$DE(*_\varphi \varphi)(\psi) = -\Delta_\varphi \psi + \text{l.o.t.}$$

for every closed $\psi \in C^\infty(M, \Lambda^4)$ and the proof of Theorem 1.2 follows.

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