

Modeling, Estimation, and Optimal Control of Anti-COVID-19 Multi-dose Vaccine Administration

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Abstract—The recent trends of the COVID-19 research are being devoted to disease transmission modeling in presence of vaccinated individuals, while the emerging needs are being focused on developing effective strategies for the optimal distribution of vaccine between population. In this context, we propose a novel non-linear time-varying model that effectively supports policy-makers in predicting and analyzing the dynamics of COVID-19 when partially and fully immune individuals are included in the population. Differently from the related literature, where the common strategies typically rely on the prioritization of the different classes of individuals, we propose a novel Model Predictive Control approach to optimally control the multi-dose vaccine administration in the case the available number of doses is not sufficient to cover the whole population. Focusing on the minimization of the expected number of deaths, the approach discriminates between the number of first and second doses. We calibrate the model on the Israeli scenario using real data and we estimate the impact of the vaccine administration on the virus dynamics. Lastly, we assess the impact of the first dose of the Pfizer's vaccine confirming the results of clinical tests.

Index Terms—COVID-19, pandemic modeling, vaccine, vaccine distribution, model predictive control.

I. INTRODUCTION

In order to properly analyze the spread of COVID-19 contagions, predict its dynamics, and support decision makers in defining effective mitigating actions, several mathematical models have been developed.

One of the main problems in epidemiological modelling relies in the proper estimation of the involved parameters, requiring widespread data, which are however seldom available in the early stages of any pandemic.

In addition, since many countries worldwide are organized into separate administrative areas with different shares of the national healthcare system, another group of works deepens the analysis at a regional level [1], [2].

The first COVID-19 vaccines have already begun to be administered to population in all countries. Consequently, most contributions on COVID-19 modeling are focusing on

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models that include additional classes of the population to suitably represent vaccinated individuals [3]. At the same time, several countries around the world are struggling to complete the vaccination campaigns in the shortest time possible. However, the limited amount of vaccine doses is making this task challenging and almost impossible in a short period. As for other epidemics, intelligent decision making strategies have been effectively used to plan the vaccination in the absence of a sufficient number of doses [4].

As for COVID-19, several vaccine allocation strategies have been proposed [5]. For instance, in [6] the authors employ a mathematical model to compare five age-stratified prioritization strategies in order to reduce existing inequities in COVID-19 vaccine distribution. In [7] a model for the optimal vaccine allocation is proposed and applied for the Korean scenario. The strategic spatio-temporal distribution of vaccines is investigated in [8], with the final aim of prioritizing the distribution in those areas where there are the most new cases of infection during a fixed time period. Referring to optimal control strategy, in [3] the authors propose an optimal control strategy for vaccine administration in the COVID-19 pandemic.

A viable option proposed by some researchers to overcome the lack of vaccine for the COVID-19 pandemic lies in delaying the injection of the second dose. To date, the UK is the only country that is delaying the second dose to 12 weeks [9]. Clinical trials suggest that delaying the second dose to 12 weeks may lower the efficacy of the vaccine until a point where the effect of the second dose becomes negligible and thus comparable with a single-dose vaccination. In fact, clinical reports demonstrate 52,4% of efficacy after 22 days for BNT162b2 Pfizer's vaccine first dose [10]. Moreover, an effectiveness of 50–60% in tackling the COVID-19 infections has been reported in observational cohort studies in Israel covering the same period [11]. Therefore, the high efficacy with a single dose may be sufficient for the herd immunity in absence of a sufficient number of vaccine; not surprisingly, the World Health Organization defined as a minimum 50% threshold for a vaccine to be effective, and thus a single dose can still be useful to reduce the pandemic spread when no other options are available [12].

In this paper we propose a *SIRUCQHE* epidemic model and differently from our previous contribution [2], we divide Infected individuals into Contagious and Infected yet not contagious, and we assume that Threatened people must observe a quarantine period when released from the hospital. Moreover, we remove the time dependency of the recovery

rate and we substitute the time dependency of the death rate with a function dependent on the number of Threatened people.

We deem it essential to remark that, while other literature contributions dynamically identify the model parameters by dividing the fitting period, in our work time-varying functions are presented to model the time-varying parameters. Furthermore, since the infection rate depends on people's mobility, differently from the related literature, in the fitting phase we make use of the Google mobility reports [13] to identify and predict the evolution of the infection rate.

In addition, with respect to our previous contribution [2] where the control actions are focused on enforcing restrictions on people mobility, in this work we also include in the model vaccinations and an additional class to represent partially immune individuals. Moreover, we apply the aforementioned model in conjunction with a Model Predictive Control (MPC) approach aiming at optimally planning the vaccine distribution minimizing the number of fatalities. Differently from the related literature, where the control actions aim at optimally distributing the vaccine among individuals, in the proposed approach, we assume that, in absence of a sufficient number of vaccines, decision makers can decide to employ a single vaccine dose.

To date, Israel has administered the most COVID-19 vaccine doses per capita in the world. Therefore, we apply the proposed approach to the Israeli scenario firstly estimating the effectiveness of a single vaccine dose to tackle the COVID-19 among a population and secondly showing the reliability of the proposed control model in selecting the best strategy while minimizing the numbers of fatalities.

The rest of this work is structured as follows. Section II presents the *SIRUCQTHE* model. Section III proposes the MPC framework, describing the corresponding control variables, objectives, and constraints, and formulating the comprehensive optimal allocation problem. Section IV reports the numerical outcomes achieved by the simulations based on the real data of the Israeli scenario. Finally, Section V concludes the paper highlighting possible future developments.

II. COVID-19 DYNAMICS WITH MULTI-DOSE VACCINATION

In this paper, a novel time-varying discrete-time epidemiological model for the COVID-19 spread in presence of partially and fully vaccinated individuals is proposed, named *SIRUCQHE*, which classifies individuals into eight compartments:

- *Susceptible*;
- *Infected* (infected by someone and not yet contagious);
- *Removed* (fully vaccinated or completely recovered);
- *Unsusceptible* (vaccinated and partially immune);
- *Contagious* (infected and undetected, contagious);
- *Quarantined* (infected and detected)
- *Hospitalized* (hospitalized);
- *Extinct* (detected and dead).

The *SIRUCQHE* model is thus composed of eight time-varying difference equations, which represent the dynamics

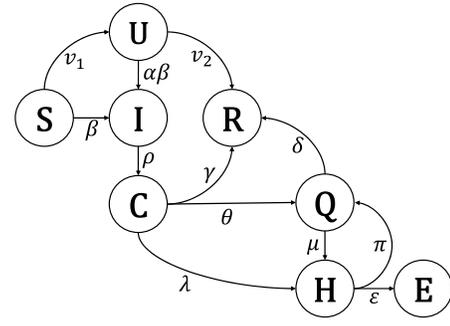


Fig. 1. Scheme of the *SIRUCQHE* model.

of individuals' flows between the various compartments. We consider as state variables of the model the fraction of the overall population related to the various compartments. Denoting by a capital Latin letter each state variable, and denoting the time step as k , the model can be written as follows:

$$S(k+1) = S(k) - \beta(k) \frac{C(k)S(k)}{N} - v_1(k - \tau_1) \quad (1)$$

$$I(k+1) = I(k) + \beta(k) \frac{C(k)S(k)}{N} + \alpha\beta(k) \frac{C(k)U(k)}{N} - \rho I(k) \quad (2)$$

$$R(k+1) = R(k) + \gamma C(k) + \delta Q(k) + v_2(k - \tau_2) \quad (3)$$

$$U(k+1) = U(k) - \alpha\beta(k) \frac{C(k)U(k)}{N} + v_1(k - \tau_1) - v_2(k - \tau_2) \quad (4)$$

$$C(k+1) = C(k) + \rho I(k) - (\gamma + \theta(k) + \lambda)C(k) \quad (5)$$

$$Q(k+1) = Q(k) + \theta(k)C(k) + \pi H(k) - (\delta + \mu)Q(k) \quad (6)$$

$$H(k+1) = H(k) + \mu Q(k) + \lambda C(k) - (\pi + \varepsilon(k))H(k) \quad (7)$$

$$E(k+1) = E(k) + \varepsilon(k)H(k) \quad (8)$$

where N represents the whole population.

The eight classes are connected by directed arcs whose weights correspond to the parameters that put in relation the corresponding classes. The overall interconnections between the above compartments are shown in Fig.1.

In particular, $\beta(k) \in \mathbb{R}_+$ is the time-varying infection rate, whose value depends on the population behavior and the adopted social distancing measures. The parameter $\alpha \in [0 - 1]$ describes how effective a single dose of the vaccine is, e.g. when $\alpha = 0$ only the first injection is fully effective to prevent an infection. Moreover, $v_1(k) \in \mathbb{Z}_+$ and $v_2(k) \in \mathbb{Z}_+$ represent the number of first and second vaccine doses made at time k , respectively. Parameters $\tau_1 \in \mathbb{Z}_+$ and $\tau_2 \in \mathbb{Z}_+$ define the average time required to develop an immune response after the first and the second dose. Parameter $\theta(k) \in \mathbb{R}_+$ is the time-varying detection rate that describes the rate of Contagious people that are recognized and Quarantined; this must be modeled as a time-varying parameter since it largely depends on the epidemiological situation. As will be demonstrated in Section IV, parameter $\beta(k)$ can be correlated with people's mobility through the use of the Google Mobility Reports [13] and parameter $\theta(k)$ with the ratio between new daily discovered cases and daily swabs. Parameter $\rho \in \mathbb{R}_+$ is the so-called incubation rate. Parameters $\gamma \in \mathbb{R}_+$ and $\delta \in \mathbb{R}_+$ are the so-called healing rates. However, the first describes the rate of healing of

Contagious and unrecognized people (thus, not requiring hospitalization) that are no longer infectious. In contrast, the second is the healing rate of Quarantined people who can leave this class when they are no longer infectious or legally obliged to stay at home. Parameters $\lambda \in \mathbb{R}_+$ and $\mu \in \mathbb{R}_+$ are the hospitalization rates: λ is the rate of people recognized and immediately hospitalized when a severe symptomatic condition occurs, while μ is the rate of Quarantined people that need for hospitalization. Parameter $\pi \in \mathbb{R}_+$ is the healing rate of Threatened people. Note that we assume that, after being released from the hospital, people must observe a quarantine period. Lastly, $\varepsilon(k) \in \mathbb{R}_+$ is the time-varying death rate that depends on the number of Threatened people. This relation is discussed in Section IV.

Note that, based on the current level of knowledge, we reasonably assume that the probability of becoming susceptible after being healed is negligible since the relative dynamics is much slower than the main time constant of the model [14].

The proposed model ensures a good accuracy, in representing the dynamics of the disease, also allowing to represent all the facets of the pandemic diffusion. Its simplicity helps identifying the characteristic parameters starting from the available data. In fact, various papers aiming at representing the dynamics of the COVID-19 pandemic present compartmental models, but generally lack an accurate identification of the model parameters. Therefore, with respect to the related literature in the *SIRUCQHE* model we compress or eliminate some classes, and we disregard some connections between compartments. Despite these simplifying assumptions, as shown in Section IV, the presented model is effective in the identification phase by only requiring a minimal set of epidemiological data.

III. OPTIMAL VACCINE MULTI-DOSE ADMINISTRATION

In this section we describe the proposed approach to optimally plan the multi-dose vaccine administration in order to reach the mass coverage and thus herd immunity; however, we assume that the approach takes into account the limited availability of vaccine.

We employ a receding horizon scheme and we assume that the prediction and control horizon have the same length. Specifically, at the generic sampling step $h \in \mathbb{Z}_+$ the horizon - defined as $\mathcal{K}(h) = \{h, \dots, h+K-1\}$ - contains K equally spaced time slots with length Δ_k .

Moreover, for each time step h we define a vector of control variables $\mathbf{u}(h) := (\mathbf{u}_1(h)^\top, \mathbf{u}_2(h)^\top)^\top \in \mathbb{Z}_+^{2K}$ where $\mathbf{u}_1(k) := (u_1(h), \dots, u_1(h+K-1))^\top \in \mathbb{Z}_+^K$ and $\mathbf{u}_2(k) := (u_2(h), \dots, u_2(h+K-1))^\top \in \mathbb{Z}_+^K$ collect the quantities of first and second doses that are planned to be administered over the given control horizon, respectively.

In order to avoid too frequent and impractical changes in the strategies, the control actions are kept constant over a given period equal to $\Delta_l = \omega \Delta_k$ (i.e., for ω time slots). For instance, if Δ_k corresponds to one day, it could be meaningful to set the periodicity of the control actions equal to one week (i.e., $\omega = 7$). Assuming that $K = L\omega$, with $L \in$

\mathbb{N} , the following additional constraints are then introduced to keep the control actions constant in each period l :

$$u_1(\omega l + 1) = u_1(\omega l + 2) = \dots = u_1(\omega l + \omega), \forall l = 0, \dots, L-1 \quad (9)$$

$$u_2(\omega l + 1) = u_2(\omega l + 2) = \dots = u_2(\omega l + \omega), \forall l = 0, \dots, L-1. \quad (10)$$

Furthermore, as we aim at planning the vaccine distribution in the case the number of doses are scarce, we include an additional constraint on the total number of available doses. Since in most countries the vaccine doses are not distributed on a daily basis, we assume this constraint must be fulfilled over the given period equal to Δ_l . As a consequence, let us define the aforementioned constraint as:

$$\sum_{i=1}^{\omega} u_1(\omega l + i) + u_2(\omega l + i) \leq \bar{v}(l+1), \forall l = 0, \dots, L-1 \quad (11)$$

where vector $\bar{v}(l+1)$ is the maximum number of vaccine doses for the period l .

As the number of people in a compartmental model cannot be negative, we include the following constraints that should be respected while planning the vaccine administration:

$$v_1(k) \leq S(k), \quad v_2(k) \leq U(k). \quad (12)$$

Lastly, we assume that the number of second doses cannot be chosen independently from the previously made first doses. In fact, clinical tests reported a maximum efficacy for the second dose only if this is administered no later than a given maximum time period from the administration of the first dose. Therefore, here we assume that the second dose can be made only between a characteristic time window after the first injection. Moreover, we assume that if a person does not receive the second injection in this time period then it will not receive it anymore. The resulting constraint can be written as:

$$v_2(k) \leq \sum_{\tau_1 = \tau_1^{\min}}^{\tau_1^{\max}} v_1(k - \tau_1) - \dots - \min \left\{ 0, v_2(k-1) - \sum_{\tau_1 = \tau_1^{\min} + 2}^{\tau_1^{\max} + 1} v_1(k - \tau_1) \right\} \quad (13)$$

where τ_1^{\min} is the minimum time that must elapse between the first and the second dose (e.g, for the BNT162b2 Pfizer's vaccine this is 21 days) and τ_1^{\max} is the maximum delay that can be accepted for the second injection.

Having defined the constraints that the vaccine distribution must follow, let us remark that the proposed MPC approach aims at optimizing the distribution of the vaccine doses while minimizing the number of deaths. Therefore, on the basis of the above defined control variables and related constraint set and the corresponding state model, the optimal control problem is defined as follows:

$$\begin{aligned} & \underset{\mathbf{u}(h)}{\text{minimize}} && J(\mathbf{u}(h)) = E(h+K-1) - E(h) \\ & \text{subject to} && \text{SIRUCQHE model (1)-(8), } \forall k \in \mathcal{K}(h) \\ & && \text{constraints (9)-(13), } \forall k \in \mathcal{K}(h). \end{aligned} \quad (14)$$

For the sake of taking the variability and uncertainty of the model parameters into account, we employ a rolling horizon framework; hence, we solve the optimization problem (14) at each ω time step in an iterative manner, based on the most recent input data. The obtained control actions related to the first time step are applied to the system to steer its behavior to the desired one, while the horizon is shifted forward. Then, a new optimization problem is solved over the shifted prediction horizon, based on the updated information on forecasts and system states.

It must be noticed that the presented closed-loop feedback control technique may depend on quantities that are both directly and not directly measurable. In effect, an identification procedure should be performed at each time step for the *SIRUCQHE* model, since the related classes cannot be not all directly estimable. In particular, the identification procedure consists in using, at each time step, the most recent data related to the available classes to dynamically update the remaining *SIRUCQHE* parameters. We discuss this aspect in the case study section.

IV. CASE STUDY

This section is divided into two parts. In the first part, we describe the main assumptions on the system parameters and the fitting procedure, while in the second part we present some numerical simulations based on the proposed control framework.

A. Parameters Identification

Let us explain how we calibrate the *SIRUCQHE* model with respect to the Israeli scenario based on real data obtained from [15].

Hereafter, we detail the assumptions considered for each of the model parameters.

1) $\beta(k)$: The so-called infection rate $\beta(k)$ for the COVID-19 pandemic is usually assumed within 0.25 and 0.8 in the absence of any social distancing policies and people awareness. Following [16], [17] and [18], we assume that the infection rate is strongly influenced by people's mobility in different socio-economic categories denoted by $\mathcal{G} = \{1, \dots, G\}$. Hence, we assume that the infection rate can be decomposed into different terms each of which is mainly affected by a given category. We consider that a reduction of the mobility associated with the different socio-economic categories can be, with a good approximation, represented with a linear decrease of the infection rate as follows:

$$\beta(k) = \beta_0 + \beta^\top \mathbf{m}(k) \quad (15)$$

where β_0 is the infection rate not explicable with a variation of the mobility (e.g., household infection), $\beta = (\beta_1, \dots, \beta_G)^\top$ is the column vector collecting the term β_g of the infection rate corresponding to each socio-economic category $g \in \mathcal{G}$, and $\mathbf{m}(k) = (m_1(k), \dots, m_G(k))^\top$ is the column vector collecting the mobility level $m_g(k)$ at time step k for each socio-economic category $g \in \mathcal{G}$. We assume that $m_g(k) = 1$ when the g -th category's mobility level equals the nominal value, i.e., the value in absence of mobility restrictions.

We estimated the evolution of people's mobility in different categories through the Google Mobility Reports [13]. We select the *Workplaces*, *Retail & recreation*, and *Public transport* categories as the most significant in terms of socio-economic importance. Hence, we define $\mathbf{m}(k) = (m_1(k), m_2(k), m_3(k))^\top$ and $\beta = (\beta_1, \beta_2, \beta_3)^\top$, indicating respectively the mobility level of *Workplaces*, *Retail and recreation* and *Public transport*.

2) ρ : The so-called incubation rate ρ is the rate of infected people that become contagious and can consequently infect other people. In the literature, the incubation time is estimated between 2 and 7 days [19], [20].

3) γ : The healing rate of unrecognized Contagious people γ can be approximated by a constant. In particular, literature findings show that the healing time is approximately 14 days. However, in our model, we do not remove people from the Contagious compartment when they are completely healed, but only when they are not contagious or have a really low viral load. In the literature, this period is estimated between 3 and 10 days [21]–[24].

4) δ : The healing rate of Quarantined people who do not need hospitalization δ can also be approximated by a constant value and can be substituted with γ when a person is removed from the Quarantined compartment immediately after he/she becomes not contagious. However, in several countries, someone may be forced to be in quarantine even after being clinically healed because the procedure requires two negative tests.

5) $\theta(k)$: Parameter $\theta(k)$ models the rate of Contagious people recognized and Quarantined, the so-called detection rate. Numerous research studies pointed out that the ratio $r(k) = p(k)/w(k)$ between new daily discovered cases $p(k)$ and the daily swabs $w(k)$ is crucial to understand how the tracking system is operating. When this ratio increases, it means that the tracking system is not working well and that the pandemic is out of control. Conversely, when this number is low, it means that few cases have been recognized with respect to the total amount of analyzed swabs: therefore, the pandemic is under control. Note that the aforementioned assumptions only hold when the tests are made in a stochastic way. In fact, if a country has a well-organized tracking system, it can perform only the necessary tests on people surely infected. Therefore, to consider the variability of parameter $\theta(k)$, we relate it with the aforementioned ratio as:

$$\theta(k) = \theta_0 (1 - r(k)). \quad (16)$$

It should be noted that this parameter is the most critical in COVID-19 modeling due to the high number of asymptomatic individuals. Therefore, this relation is not accurate but our experiments show that it helps the results of the identification process.

6) λ and μ : These parameters are the hospitalization rates, i.e., the rate of people recognized only when severe symptomatic conditions occur and the rate of Quarantined people to be hospitalized, respectively. We assume these two parameters are constant.

7) π : The recovery rate π during the first outbreak of COVID-19 was far from being constant; in fact, the national healthcare system was not prepared and did not have healing procedures. However, after the implementation of new standardized clinical approaches, we can assume that this parameter is constant.

8) $\varepsilon(k)$: The death rate ε at the beginning of a new epidemic is not constant and hopefully decreases with time. This is mainly due to the availability of new clinical treatments. The death rate for each time step k can be formulated as:

$$\varepsilon(k) = (E(k) - E(k-1)) / T(k). \quad (17)$$

With the pandemic's development, this parameter becomes easily identifiable, and it only depends on how much the healthcare system is under pressure.

9) τ_1 and τ_2 : The delays τ_1 and τ_2 are the characteristic average times required to develop an immune response after the first and the second vaccine doses. These values vary depending on the vaccine.

In order to estimate the above listed parameters of the proposed *SIRUCQHE* model, a least-squares optimization technique is adopted combined with constraints to enforce the prior scientific knowledge of the COVID-19 pandemic.

We firstly estimate the death rate, that we assume to follow a linear relation with the number of hospitalized individuals with coefficients ε_0 and ε_1 . The estimation of such coefficients consists in minimizing the mean squared error (MSE) of the linear approximation with respect to the real data, which is defined as:

$$\text{MSE}(\varepsilon_0, \varepsilon_1) = \frac{1}{K} \sum_{k=1}^K \left(\frac{(\varepsilon_0 + \varepsilon_1 T(k)) - \varepsilon(k)}{\varepsilon(k)} \right)^2 \quad (18)$$

Consequently, by defining Ξ_1 as the vector collecting all the unknown parameters and the initial conditions are the only parameters to be estimated, we minimize the MSE of the model with respect to real data as follows:

$$\begin{aligned} \text{MSE}(\Xi_1) = & \frac{1}{K} \sum_{k=1}^K \left(\frac{\hat{Q}(\Xi_2, k) - Q(k)}{Q(k)} \right)^2 \\ & + \frac{1}{K} \sum_{k=1}^K \left(\frac{\hat{H}(\Xi_2, k) - H(k)}{H(k)} \right)^2 \end{aligned} \quad (19)$$

For the sake of brevity we do not report here the results of the comparison between simulation model and the actual data of the considered case study. However, we report that the maximum error for the considered scenario on the Hospitalized class is approximately 20%.

In order to estimate the impact of the vaccination on the model parameters, the identification is divided into two different phases. In the first phase, we estimate the model parameters in absence of vaccination, i.e., before the Israeli vaccination campaign started on December 19, 2020. In this way, we define reasonable and tight bounds for the parameters. Consequently, in the second phase, we perform the identification with the epidemiological data during the vaccination campaign to estimate the parameter α to assess

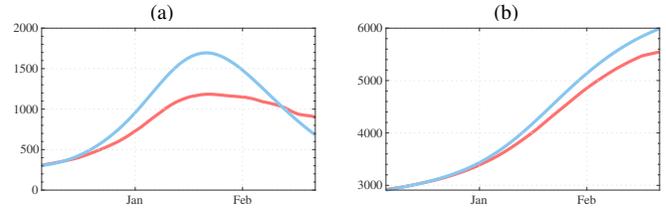


Fig. 2. Real data (red line) and results of the simulation (blue line) for the *SIRUCQHE* model without the impact of the vaccination campaign: Hospitalized (a) and Extinct (b).

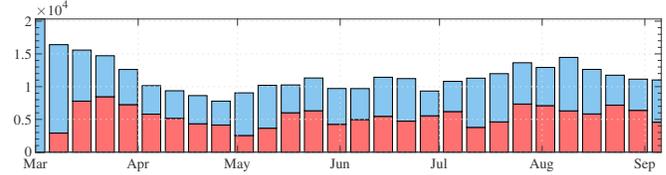


Fig. 3. Vaccine doses distribution over the simulation horizon: first doses (blue) and second doses (red).

the effectiveness of a single vaccine dose. We highlight that, in this phase, we use the previously defined bounds on the remaining parameters to make an accurate estimation of the vaccination impact. The results show that this parameter is approximately halving the infection rate, i.e., $\alpha = 0.5851$, thus confirming the results of the clinical reports.

In Fig. 2, we show the results of the *SIRUCQHE* for compartments H and E . In particular, we show the real data (with the effect of the vaccination campaign) and the forecasting of the model not considering the vaccinations. From the figure, it is clear the impact that the vaccination campaign had on preventing another outbreak of the virus.

B. Optimal Distribution of the Vaccine Doses

This subsection describes the numerical simulations based on the proposed MPC approach aimed at optimally controlling the doses' distribution. We test the approach over a simulation period of 20 weeks starting from March 5, 2021, using a prediction horizon of 10 weeks. The sampling interval Δ_k is set to one day. A daily change of the vaccination measures would be unrealistic in a real-life scenario, therefore, we assume weekly based control actions (i.e., $L = 6$ and $\Delta_l = \omega \Delta_k$, with $\omega = 7$). We consider the availability of a variable quantity of the vaccine to simulate shortage in the distribution. As for time parameters τ_1^{\min} and τ_1^{\max} , we select them based on the BNT162b2 Pfizer's vaccine clinical report and thus we set them equal to 21 and 35 days, respectively.

As a first result, in Fig. 3 we show the administration of the first and the second dose. In particular, we show a stacked bar chart that indicates in blue the administration of the first doses of vaccine and in red the second one. The proposed control strategy is able to dynamically modify the vaccination plan even with a sudden change in the vaccine administration while minimizing the number of fatalities.

Furthermore, we show the effectiveness of the proposed procedure in Fig. 4, where we plot the results of the nu-

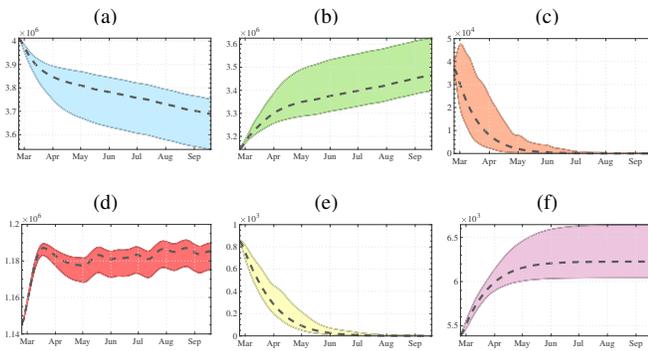


Fig. 4. Results of the simulation for the *SIRUCQHE* model: Susceptible (a), Removed (b), Contagious (c), Unsusceptible (d), Hospitalized (e), Extinct (f). Results of the simulation (dashed line) and the 20% estimated bounds (colored bands).

merical simulation for compartments S , R , C , U , H , and E under the effects of the MPC control. First of all we note that the dynamics of the Contagious and Hospitalized compartments (Fig. 4 (c) and Fig. 4 (e), respectively) tends to zero in about three months, conversely, after the same amount of months the number of Unsusceptible and Extinct people (Fig. 4 (d) and Fig. 4 (f), respectively) tend to steady state. In the figure, we add also an estimation of the system dynamics made by modifying the characterized parameters by 20% indicated by the colored bands. The results show that the proposed approach can effectively reduce the development of the pandemic leading to pandemic extinction after few months even in the presence of uncertainty. It is worth noting that, at the end of the simulation, almost 1.3 million people receive only a single injection. This confirms that, in order to reach herd immunity in the shortest time, it is possible to administrate a single dose of vaccine to the population.

V. CONCLUSIONS

Due to the limited amount of currently available vaccine doses, to date, it is crucial to develop suitable methods to support policy-makers in efficiently planning the vaccine distribution between population. To answer this challenging need, this paper presents a novel epidemiological *SIR*-based model aimed at representing the system dynamics and predicting its evolution when partially and fully immune individuals are included. Leveraging on this model, and aiming at minimizing the expected number of deaths, we present a novel Model Predictive Control approach to optimally allocate the number of first and second doses between population.

Future research will address enhancing the model by introducing age-differentiated compartments to effectively distribute the vaccine between different classes of population.

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